Dimensionality Reduction Part 1: PCA and KPCA

Ng Yen Kaow

Dimensionality Reduction

- Linear methods
 - **PCA** (Principal Component Analysis)
 - CMDS (Classical Multidimensional Scaling)
- Non-linear methods
 - **KPCA** (Kernel PCA)
 - mMDS (Metric MDS)
 - Isomap
 - LLE (Locally Linear Embedding)
 - Laplacian Eigenmap
 - t-SNE (t-distributed Stochastic Neighbor Embedding)
 - UMAP (Uniform Manifold Approximation and Projection)

- □ Let *X* be an $n \times m$ matrix where each row represents a datapoint in an *m*-D space
 - X is like a spreadsheet with features in column and data cases in the rows
- □ We want to identify some form of "principal directions" of X, where ideally
 - 1. The directions should form a basis
 - 2. The directions should be orthogonal
 - 3. The first direction should account for the most variation, the second direction accounts for the most variation after removing the first, and so on

- □ Assume datapoints in *X* are generated by a random vector $X = [v_1, ..., v_m]$, where each v_i is a random variable
 - Covariance $\operatorname{cov}(\boldsymbol{v}_i, \boldsymbol{v}_j) = \mathbb{E}[(\boldsymbol{v}_i \mu_i)(\boldsymbol{v}_j \mu_j)]$
 - Define covariance matrix $M = (m_{ij})$ of Xwhere $m_{ij} = cov(v_i, v_j)$

(*M* can be estimated from $X = (x_{ij})$ as the outer product $X^{c^{\top}}X^{c}/n$ of a centered matrix $X^{c} = (x_{ij}^{c})$ where $x_{ij}^{c} = x_{ij} - \mu_{i}$)

□ For the first principal direction, we want to find unit vector $u \in \mathbb{R}^m$ such that variance $var(u^T X)$ is maximized

□ The eigenvector u of the covariance matrix M of X with the largest eigenvalue maximizes $var(u^T X)$ Gives a matrix

since X and μ are

column vectors

Let $X \in \mathbb{R}^m$ be a random vector with

- mean vector $\mu \in \mathbb{R}^m$ and
- covariance matrix $M = \mathbb{E}[(X \mu)(X \mu)^{\top}]$

For any $u \in \mathbb{R}^n$, the projection of $u^T X$ has

•
$$\mathbb{E}[u^{\mathsf{T}}X] = u^{\mathsf{T}}\mu$$
 and
• $\operatorname{var}(u^{\mathsf{T}}X) = \mathbb{E}[(u^{\mathsf{T}}X - u^{\mathsf{T}}\mu)^2]$
= $\mathbb{E}[u^{\mathsf{T}}(X - \mu)(X - \mu)^{\mathsf{T}}u] = u^{\mathsf{T}}Mu$

From min-max theorem, $u^{\top}Mu$ is maximized when u is the eigenvector of M with the largest eigenvalue

- \square Extend to k principal directions, we want
 - *k*-D subspace of *X* that is defined by orthogonal basis $p_1, \ldots, p_k \in \mathbb{R}^m$ and displacement $p_0 \in \mathbb{R}^m$
 - Distance from X to this subspace is minimized
 - Projection of X onto subspace is $P^{\top}X + p_0$, where P is matrix whose rows are p_1, \dots, p_k
 - Squared distance to subspace is $\mathbb{E} \| \mathbf{X} (P^{\mathsf{T}} \mathbf{X} + p_{\mathbf{0}}) \|^2$
 - By calculus, $p_0 = \mathbb{E} || \mathbf{X} P^\top \mathbf{X} || = (1 P^\top) \mu$, hence $\mathbb{E} || \mathbf{X} - (P^\top \mathbf{X} + p_0) ||^2 = \mathbb{E} || \mathbf{X} - \mu ||^2 - \mathbb{E} || P^\top (\mathbf{X} - \mu) ||^2$
 - To maximize that, need to maximize $\mathbb{E} \|P^{\top}(X \mu)\|^2 = \operatorname{var}(P^{\top}X)$
 - Finally, same as in previous slide, p_1, \dots, p_k are eigenvectors of M

■ As mentioned, given a centered matrix $X^{c} = (x_{ij}^{c})$ where $x_{ij}^{c} = x_{ij} - \mu_{i}$, an unbiased estimator of *M* can be obtained as $M = \frac{1}{n} X^{c^{T}} X^{c}$ (or $M = \frac{1}{n} \sum_{i} x_{i}^{c^{T}} x_{i}^{c}$)

This implies that M is positive semi-definite

- □ Since SVD of *X* eigendecomposes $X^{c^{\top}}X^{c}$
 - We can solve PCA through either
 - 1. Eigendecompose *M*, or
 - 2. Solve SVD for X^c

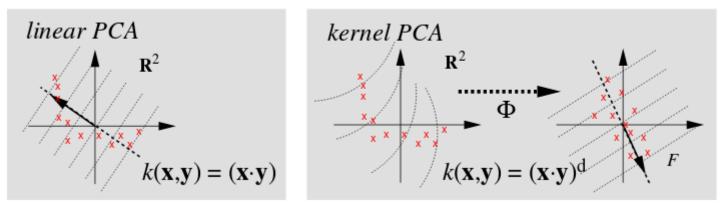
Advantages of PCA with SVD

- SVD of matrix X^c performs a eigendecomposition of $X^{c^{\top}}X^c$
 - No need to compute $X^{c^{\top}}X^{c}$
 - Given SVD of $X^c = USV^{\top}$,
 - \Box V is the eigenvectors of $X^{c^{\top}}X^{c}$
 - \Box S² is the eigenvalues of $X^{c^{\top}}X^{c}$
 - $\Box \quad \text{Since } X^c V = U S V^\top V = U S$

⇒ US gives the projection of X^c on the principal directions V (called principal component scores)

Kernel PCA motivation

 Datapoints that do not lie on a linear manifold in the coordinate space may lie on one after some non-linear feature map φ to a high dimensional space



Scholkopf, Smola, and Muller. Kernel Principal Component Analysis, 1999

Principal components in the ϕ -mapped feature space may be more meaningful

Kernel PCA idea

Steps to get the principal components in a ϕ -mapped feature space:

1.
$$x' = \phi(x)$$
 and $X' = [x_1' \dots x_n']^{\top}$

- 2. Center X' (deduct column mean)
- 3. Find covariance matrix, $M' = \frac{1}{n} \sum_{i} x_i'^{\top} x_i'$
- 4. Eigendecompose M'
- □ Difficult since dimension of x', dim(x') will be large (or even ∞)
 - \Rightarrow M' has large (or even ∞) dimensions
 - ⇒ Eigendecomposition of M' gives large (or infinite) number of eigenvectors, each of large (or infinite) dimensions

Kernel PCA idea

Problem 1: Large number of eigenvectors

- How many eigenvectors are there actually
 - rank(M'), bounded by the number of datapoints
 - □ Recall that eigenvectors can be expressed as a linear combination of the datapoints by solving the equations $x'_i = \sum_j \langle x'_i, u_j \rangle u_j$
 - *j* is bounded by $rank(M') \Rightarrow may$ be manageable
 - However, working with the system of equations is hard because x_i' and u_j are of...

Problem 2: Large (or ∞) dimensions

Kernel method

- Do not compute $\phi(x_1), \dots, \phi(x_n)$ or eigenvectors of M'
 - Allow only comparisons between datapoints in mapped space through inner product $\langle x'_i, x'_i \rangle$
 - Sufficient for writing eigenvector u of M' in terms of $\phi(x_1), \dots, \phi(x_n)$ (i.e. project u onto $\phi(x_1), \dots, \phi(x_n)$)
 - \Box Sufficient for finding the eigenvalues of M'
 - Given point x, sufficient for finding the projection of $\phi(x)$ on the eigenvectors of M'
 - Use a function $K(x_i, x_j)$ (called a kernel function) that does not require computing ϕ to compute $\langle x'_i, x'_j \rangle$

Conditions for such a function given in later slides

Project eigenvector to x'_1, \ldots, x'_n

- □ Relate eigenvectors of M' with $x'_1, ..., x'_n$ using a computation that involves only $\langle x'_i, x'_j \rangle$
- □ Start with the definition of $M' = \frac{1}{n} \left(\sum_{i=1}^{n} x_i'^{\top} x_i' \right)$
 - Solving $M'u = \lambda u$ means $(\sum_i x_i'^T x_i')u = n\lambda u$
 - This implies $u = \frac{1}{n\lambda} \sum_{i} x_{i}^{\prime \mathsf{T}} x_{i}^{\prime} u$. Since $x^{\mathsf{T}} x_{u}^{\mathsf{Proof later}} x_{u}^{\mathsf{T}} x_{u}^{\mathsf{T}} = \frac{1}{n\lambda} \sum_{i} x_{i}^{\prime} u x_{i}^{\prime \mathsf{T}}$

Hence can let $u = \sum_{i=1}^{n} \alpha_i x_i^{\prime \top}$ for $\alpha_i \in \mathbb{R}$

 $\Box \quad \alpha_1, \dots, \alpha_n \text{ project eigenvector } u \text{ to } x'_1, \dots, x'_n$

 $\square \quad \text{Place } u^{(r)} = \sum_{i} \alpha_{i}^{(r)} x_{i}^{\prime \top} \text{ back in } \left(\sum_{i} x_{i}^{\prime \top} x_{i}^{\prime} \right) u = n\lambda u$

Use superscript r to associate α with its corresponding u and λ

(Terms in bold cannot be reordered) Solving $\alpha_1, \ldots, \alpha_n$ System of dim(u) equations $\left(\sum_{i=1}^{n} {\boldsymbol{x}'_{i}}^{\mathsf{T}} {\boldsymbol{x}_{i}}'\right) \boldsymbol{u}^{(r)} = n\lambda^{(r)} \boldsymbol{u}^{(r)}$ Replace $\boldsymbol{u}^{(r)}$ with $\sum_{i} \alpha_{i}^{(r)} \boldsymbol{x}_{i}^{\prime \top}$ $\left(\sum_{i=1}^{n} \mathbf{x}_{i}^{\prime \top} \mathbf{x}_{i}^{\prime}\right) \sum_{i=1}^{n} \alpha_{i}^{(r)} \mathbf{x}_{i}^{\prime \top} = n\lambda^{(r)} \sum_{k=1}^{n} \alpha_{k}^{(r)} \mathbf{x}_{k}^{\prime \top}$ Reorder $\left(\sum_{i} \mathbf{x}_{i}^{\prime \mathsf{T}}\right) \sum_{i} \mathbf{x}_{i}^{\prime} \mathbf{x}_{i}^{\prime \mathsf{T}} \alpha_{i}^{(r)} = n\lambda^{(r)} \sum_{k} \mathbf{x}_{k}^{\prime \mathsf{T}} \alpha_{k}^{(r)}$ Multiply from the left with x'_l (equation holds for each l) System of one equation $\left(\sum_{i} \mathbf{x}_{l}^{\prime} \mathbf{x}_{i}^{\prime \top}\right) \sum_{j} \mathbf{x}_{i}^{\prime} \mathbf{x}_{j}^{\prime \top} \alpha_{j}^{(r)} = n\lambda^{(r)} \sum_{k} \mathbf{x}_{l}^{\prime} \mathbf{x}_{k}^{\prime \top} \alpha_{k}^{(r)}$

Replace $x_i' x_i'^{\mathsf{T}}$ with the kernel function

$$\sum_{i} K(x_{l}, x_{i}) \sum_{j} K(x_{i}, x_{j}) \alpha_{j}^{(r)} = n\lambda^{(r)} \sum_{k} K(x_{l}, x_{k}) \alpha_{k}^{(r)}$$
Reorder

$$\sum_{\substack{i \ge 2021. \text{ Ng Yen Kaow}}} K(x_l, x_i) K(x_i, x_j) \alpha_j^{(r)} = n\lambda^{(r)} \sum_k K(x_l, x_k) \alpha_k^{(r)}$$

Solving $\alpha_1, \ldots, \alpha_n$

$$\sum_{i} \sum_{j} K(x_l, x_i) K(x_i, x_j) \alpha_j^{(r)} = n\lambda^{(r)} \sum_{k} K(x_l, x_k) \alpha_k^{(r)}$$

Replace $K(x_i, x_j)$ with a matrix K where $k_{ij} = K(x_i, x_j)$ (K is called a kernel matrix)

$$\sum_{i} \sum_{j} k_{li} k_{ij} \alpha_{j}^{(r)} = n \lambda^{(r)} \sum_{k} k_{lk} \alpha_{k}^{(r)}$$

□ For each *l* this gives one single equation with a linear combination of the variables $\alpha_1^{(r)}$, ..., $\alpha_n^{(r)}$

$$\begin{array}{l} \bullet \text{ e.g. } l = 2 \\ K_{1}^{\mathsf{T}} & K_{2}^{\mathsf{T}} \\ K_{l} \rightarrow \begin{bmatrix} k_{11} & k_{12} & \cdots \\ k_{21} & k_{22} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} k_{11}^{\mathsf{T}} & k_{12}^{\mathsf{T}} \\ k_{21}^{\mathsf{T}} & k_{22}^{\mathsf{T}} \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_{1}^{(r)} \\ \alpha_{2}^{(r)} \\ \vdots \\ \vdots \end{bmatrix} = n\lambda^{(r)} \begin{bmatrix} k_{11} & k_{12} & \cdots \\ k_{21} & k_{22} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_{1}^{(r)} \\ \alpha_{2}^{(r)} \\ \vdots \\ \vdots \end{bmatrix} \\ (k_{21}k_{11} + k_{22}k_{21} + \cdots)\alpha_{1}^{(r)} + (k_{21}k_{12} + k_{22}k_{22} + \cdots)\alpha_{2}^{(r)} + \cdots \\ = n\lambda^{(r)} \left(k_{21}\alpha_{1}^{(r)} + k_{21}\alpha_{2}^{(r)} + \cdots \right) \right)$$

Solving
$$\alpha_1, \dots, \alpha_n$$

 $K_1^{\mathsf{T}} \quad K_2^{\mathsf{T}}$
 $K_1^{\mathsf{T}} \quad K_2^{\mathsf{T}}$
 $K_1 \wedge \begin{pmatrix} k_{11} & k_{12} & \cdots \\ k_{21} & k_{22} & \cdots \\ \vdots & \vdots & \ddots \end{pmatrix} \begin{bmatrix} k_{11} & k_{12} & \cdots \\ k_{21} & k_{22} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots \end{bmatrix} = n\lambda^{(r)} \begin{bmatrix} k_{11} & k_{12} & \cdots \\ k_{21} & k_{22} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots \end{bmatrix}$

 \square Repeat *l* for 1 to *n*

System of *n* equations

$$\begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ 1 \\ \alpha_2^{(r)} \\ \vdots \end{bmatrix} = n\lambda^{(r)} \begin{bmatrix} k_{11} & k_{12} & \dots \\ k_{21} & k_{22} & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} \alpha_1^{(r)} \\ \alpha_2^{(r)} \\ \vdots \end{bmatrix}$$

This in matrix notation is $K^2 \alpha^{(r)} = n \lambda^{(r)} K \alpha^{(r)}$

Each a^(r) that fulfills the equation gives us a eigenvector u^(r) of the covariance matrix M' in terms of the data x'_i

Solving $\alpha_1, \ldots, \alpha_n$

□ Removing *K* from both sides will only affect the $\alpha^{(r)}$ with zero $\lambda^{(r)}$ (proof omitted), leaving the final form of the eigenvalue system

 $\boldsymbol{K}\boldsymbol{\alpha}^{(r)} = n\lambda^{(r)}\boldsymbol{\alpha}^{(r)}$

□ Since ||u|| = 1, we require $n\lambda \alpha^{\top} \alpha = 1 \Rightarrow ||\alpha||^2 = 1/n\lambda \Rightarrow ||\alpha|| = \sqrt{1/n\lambda}$

However, α^* from the eigendecomposition of *K* has unit length and eigenvalue $\lambda^* = n\lambda^{(r)}$ To correct for this, $\alpha^{(r)} = \frac{\alpha^*}{\sqrt{n\lambda^{(r)}}} = \frac{\alpha^*}{\sqrt{n\lambda^*/n}} = \frac{\alpha^*}{\sqrt{\lambda^*}}$

□ Since $\lambda^{(r)} = \lambda^* / n$, the relative importance of the eigenvectors can be determined from λ^*

Proof for $||\boldsymbol{u}|| = 1 \Rightarrow n\lambda \boldsymbol{\alpha}^{\top} \boldsymbol{\alpha} = 1$ \square Since $||\boldsymbol{u}|| = 1$ $\boldsymbol{u}^{\mathsf{T}}\boldsymbol{u} = 1$ $\left(\sum_{i} \alpha_{i} \boldsymbol{x}_{i}^{\prime \top}\right)^{\mathsf{T}} \left(\sum_{i} \alpha_{i} \boldsymbol{x}_{i}^{\prime \top}\right) = 1$ $\sum_{i} \sum_{i} \alpha_{i} \alpha_{i} x_{i}' x_{i}'^{\top} = 1$ $\sum_{i} \sum_{i} \alpha_{i} K_{ii} \alpha_{i} = 1$ \square Multiply α_i to $\sum_i K_{ij} \alpha_i = n\lambda \sum_k \alpha_k$ gives $n\lambda \sum_{i} \sum_{k} \alpha_{i} \alpha_{k} = \sum_{i} \sum_{i} \alpha_{i} K_{ii} \alpha_{i}$

 $n\lambda \sum_{i} \sum_{k} \alpha_{i} \alpha_{k} = 1$ $n\lambda \boldsymbol{\alpha}^{\mathsf{T}} \boldsymbol{\alpha} = 1$

Proof for
$$x^{\mathsf{T}} x u = x u x^{\mathsf{T}}$$

 $(v^{\mathsf{T}} v)u = \begin{pmatrix} v_1 v_1 & \dots & v_1 v_n \\ \vdots & \ddots & \vdots \\ v_n v_1 & \dots & v_n v_n \end{pmatrix} \begin{pmatrix} u_1 \\ \vdots \\ u_n \end{pmatrix}$
 $= \begin{pmatrix} v_1 v_1 u_1 + \dots + v_n v_n \end{pmatrix}$
 $= \begin{pmatrix} (v_1 v_1 u_1 + \dots + v_n v_n u_n) \\ \vdots \\ (v_1 u_1 + \dots + v_n u_n) v_n \end{pmatrix}$
 $= (v_1 u_1 + \dots + v_n u_n) \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$

Projection of $\phi(x)$ on u

- Given a point y, the projection of $\phi(y)$ on the eigenvector $u^{(r)}$ of M' can be computed using $\alpha^{(r)}$ as
 - $\phi(y)u^{(r)} = \sum_{i=1}^{n} \alpha_i^{(r)} \phi(y)^{\mathsf{T}} x_i'$ $= \sum_i \alpha_i^{(r)} K(y, x_i)$
- This allows the principal components to be used for clustering existing datapoints as well as classifying out-of-sample datapoints into the clusters

Normalizing M'

- \Box X' has been assumed to be normalized so far
- □ To normalize a matrix X', subtract every column with the mean of the column:

$$x^* = x' - \frac{1}{n} \sum_{i=1}^n x'_i$$

□ The corresponding kernel,

$$K^{*}(x_{i}, x_{j}) = x_{i}^{*} x_{j}^{*} = \left(x' - \frac{1}{n} \sum_{i=1}^{n} x_{i}'\right) \left(x' - \frac{1}{n} \sum_{i=1}^{n} x_{i}'\right)$$
$$= K(x_{i}, x_{j}) - \frac{1}{n} \sum_{k=1}^{n} K(x_{i}, x_{k})$$
$$- \frac{1}{n} \sum_{k=1}^{n} K(x_{j}, x_{k}) + \frac{1}{n^{2}} \sum_{l,k=1}^{n} K(x_{l}, x_{k})$$

Or in matrix notation

$$K^* = K - 2\mathbf{1}_{1/n}K + \mathbf{1}_{1/n}K\mathbf{1}_{1/n}$$

Kernel functions

- □ A kernel function *K* implicitly defines a mapping ϕ from an input space to some feature space
- Positive semi-definite functions are those that produce positive semi-definite kernel matrices
 - Definition. A symmetric function *K* is called positive semi-definite over χ if and only if for every set of elements $x_1, \dots, x_n \in \chi$, the matrix $\mathbf{K} = (x_{ij})$ where $x_{ij} = K(x_i, x_j)$ is positive semidefinite

 Kernel functions must be positive semidefinite
 Hilbert space (ignore for now)

• **Theorem**. A mapping ϕ exists for $K: \chi \to \mathcal{H}$ such that $K(x, x') = \langle \phi(x), \phi(x') \rangle \Leftrightarrow K$ is a positive semi-definite symmetric matrix

Kernel functions

Properties

Symmetric K(x, x') = K(x', x)

Cauchy-Schwarz $|K(x, x')| \le \sqrt{K(x, x)K(x', x')}$ inequality

Definiteness	$K(x, x) = \ \phi(x)\ ^2 \ge 0$

□ Kernel property conservation

Sum	K, K' are kernels \Rightarrow K + K' is kernel
Product	K, K' are kernels $\Rightarrow KK'$ is kernel
Scaling	<i>K</i> is kernel $\Rightarrow \alpha K$ is kernel for positive real α
Polynomial combination	<i>K</i> is kernel $\Rightarrow p(K)$ is kernel for polynomial <i>p</i> of degree <i>m</i> with positive coefficients

Kernel functions

Common kernel functions

Linear	$K(x,x') = xx'^{T}$
Cosine	$K(x, x') = xx'^{\top} / x x' $
Gaussian	$K(x, x') = \exp(-\gamma x - x' ^2)$
Polynomial	$K(x, x') = (\gamma x x'^{\top} + c)^d$ for $\gamma, c \in \mathbb{R}^+, d \in \mathbb{N}^+$
Sigmoid	$K(x, x') = \tanh(\gamma x x'^{\top} + c) \text{ for } \gamma, c \in \mathbb{R}^+$

See <u>http://crsouza.com/2010/03/17/kernel-functions-for-machine-learning-applications</u> for a collection of uncommon kernel functions